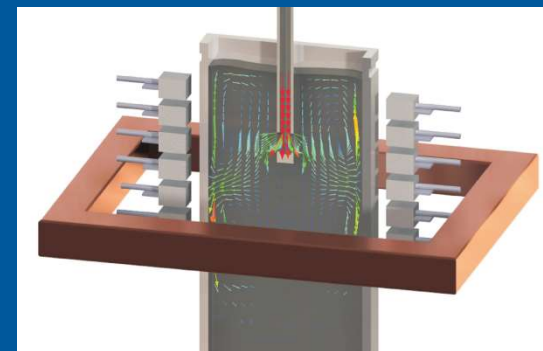


Flow measurements in liquid metals

Sven Eckert

Helmholtz-Zentrum Dresden-Rossendorf (HZDR)



Many thanks to:

Thomas Wondrak, Matthias Ratajczak, Nico Krauter,
Klaus Timmel, Sven Franke, Thomas Gundrum,
Frank Stefani, Phillip Büttner, Thomas Richter,
Natalia Shevchenko ...



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ROSSENDORF

Measurement quantities

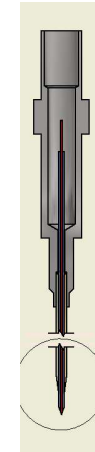
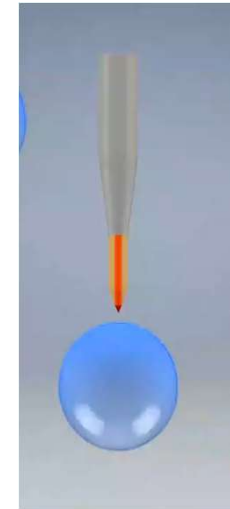
Quantity	Sensor
Pressure	Fiber optical sensors
Flow rate	Inductive flow meter
Local velocity	Mechanical devices Potential probe (turbulent spectra)
Flow field (1D/2D/3D)	Ultrasound Doppler Velocimetry Contactless Inductive Flow Tomography
Multi-phase flows	Resistance probes Fibre optical sensors Ultrasound Transit Time Technique X-ray / neutron radioscopy Mutual Inductance Tomography
Free surface level	Ultrasound methods Optical methods Inductive methods

non-invasive but
contact needed

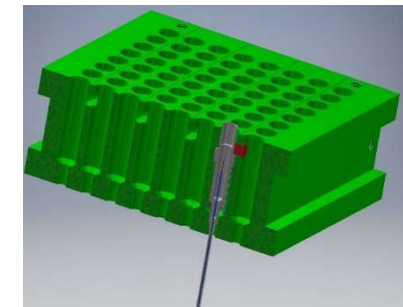
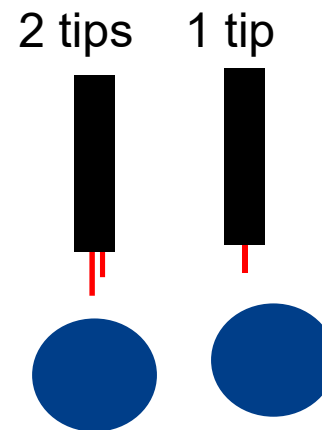
contactless

Resistive probes for local gas detection

- Insolated rod with small electrical contact at the sensor tip
- Sensor inserted into the melt
- Current flows through the liquid to the sensor top
- Gas bubbles are insulator
- Sensor signal: on/off (contact time of bubble)
- Sensors with two tips: bubble velocity
- Sensor design challenges:
 - electrical insulation
 - length of the tip
 - corrosion of the tip
 - mechanical stability

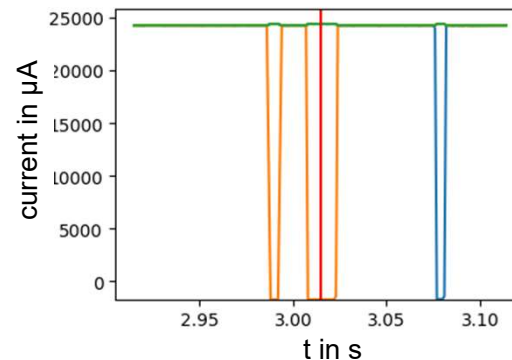
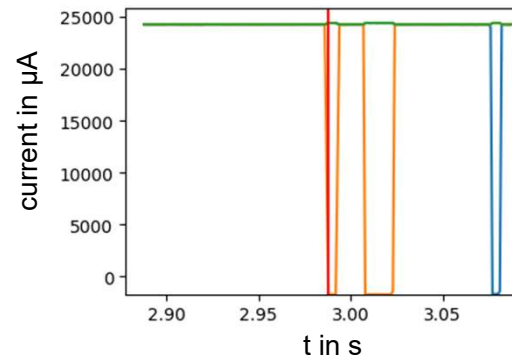


sensor design
with mounting

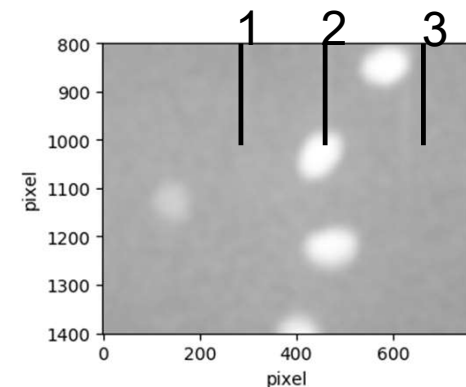
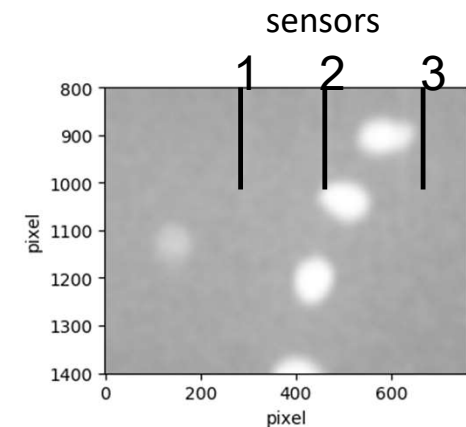


Resistive probes: validation by X-ray visualization

- Vessel cross section:
140 mm x 12 mm
- Liquid metal: GaInSn
- 3 sensors inserted at the top
- Spacing 10 mm
- Argon gas injection
at the bottom
- 1 – 10 kHz data sampling
- Synchronization with the camera
- Results:
 - negligible effect on the flow
 - bubble not centered



— sensor 1 — sensor 2 — sensor 3



Potential Probe

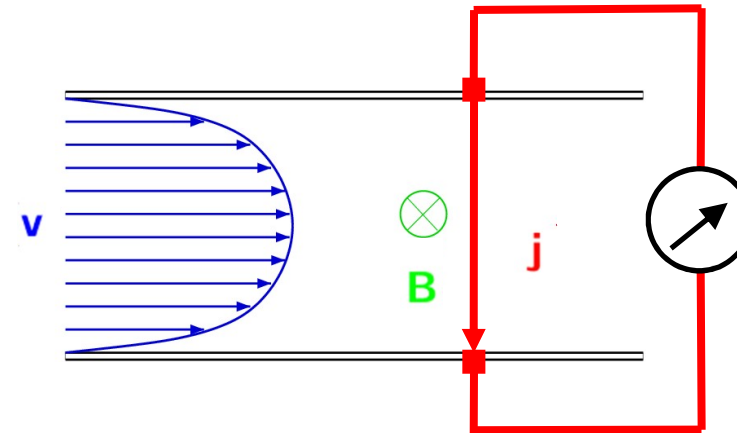
- Two electrodes with distance L in contact with the fluid
- Magnetic field \mathbf{B} generated by a small magnet incorporated into the probe or externally applied
- Ohm's law for moving conductors

$$\mathbf{j} = \sigma(\mathbf{v} \times \mathbf{B} - \nabla\varphi)$$

- Measured voltage:

$$\Delta\varphi = c_w \cdot L \cdot |\mathbf{B}| \cdot v$$

- Calibration factor: c_w
- Small response time 500 Hz: turbulent fluctuations
- Challenges:
 - Invasive
 - Prone to electrical interfering signals: nV (!)



Ultrasound Doppler Velocimetry (UDV)

- Transmission of multitude of ultrasonic bursts
- Burst reflected at scattering particles
- Position of scattering particle:

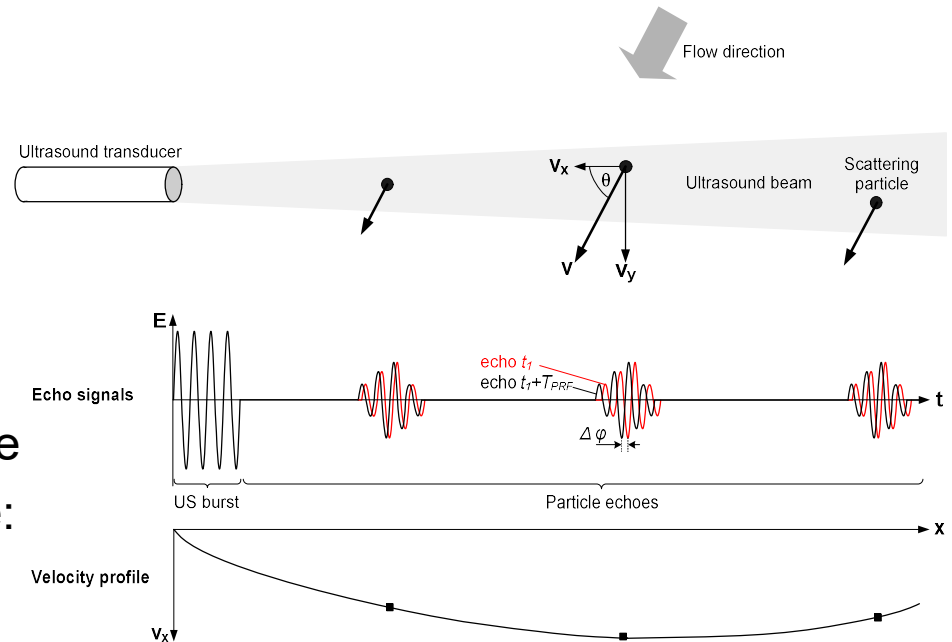
$$x = \frac{ct}{2}$$

c sound velocity

- Phase-shift between successive particle echoes referred to pulse repetition time:

$$v_x = \frac{c \cdot \Delta\phi}{4\pi \cdot f_0 \cdot T_{prf}}$$

- Instantaneous velocity profile
 - 1 mm/s ... 10 m/s
 - 20 - 30 Hz
- Can operate through wall

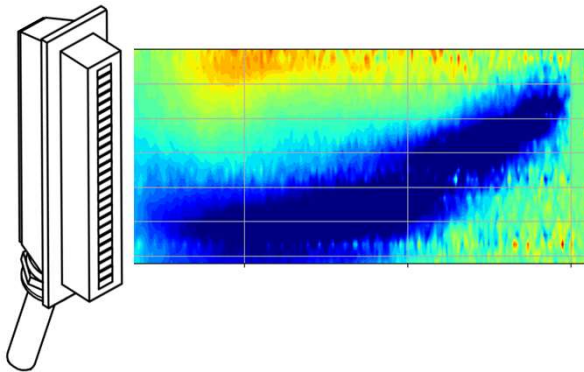
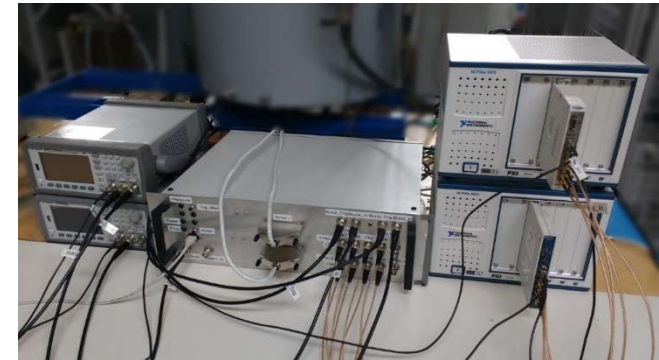


Doppler angle θ : $v = v_x \cos \theta$

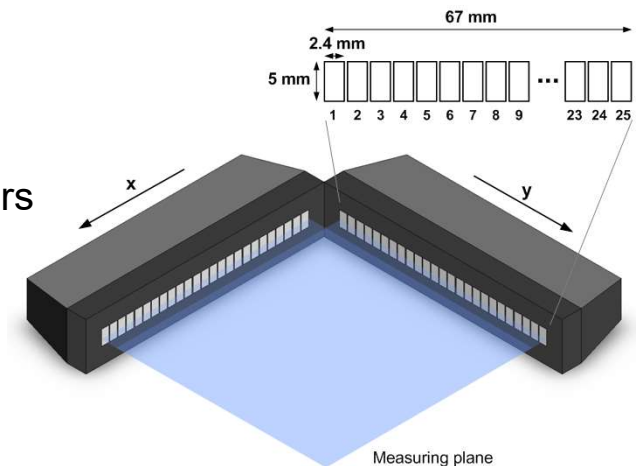
Y. Takeda, Ultrasonic Doppler velocimetry profile for fluid flow (2012) Springer


Ultrasound sensor array

	state of the art	new array
Imaging dimensions	2D-1C	$\geq 2D-2C$
Measuring lines	≤ 21	≥ 48
Meas. line sampling	sequential	parallel
Measurement rate	5 fps	≥ 30 fps
Measuring line pitch	≥ 8 mm	< 3 mm



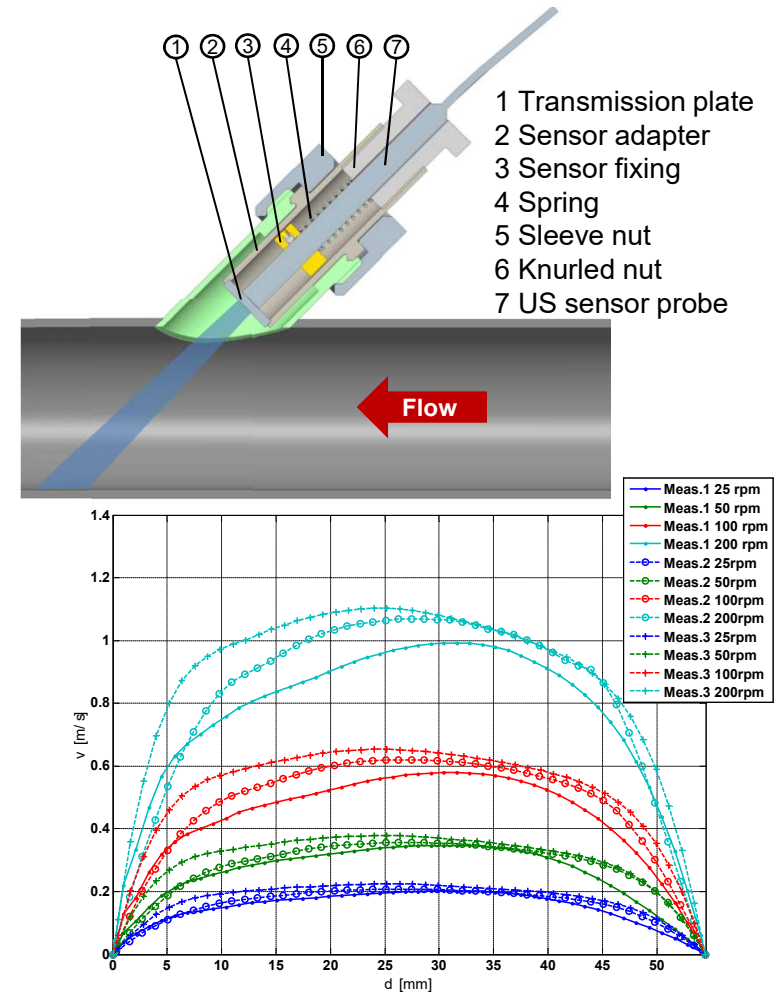
- Up to 4 linear transducer arrays
- Measuring plane: $67 \times 67 \text{ mm}^2$
- Measurement grid: 24×24 vectors
- Grid pitch: 2.7 mm
- Spatial resolution: $\approx 3 \text{ mm}$



 S. Franke et al., Ultrasonics (2013)

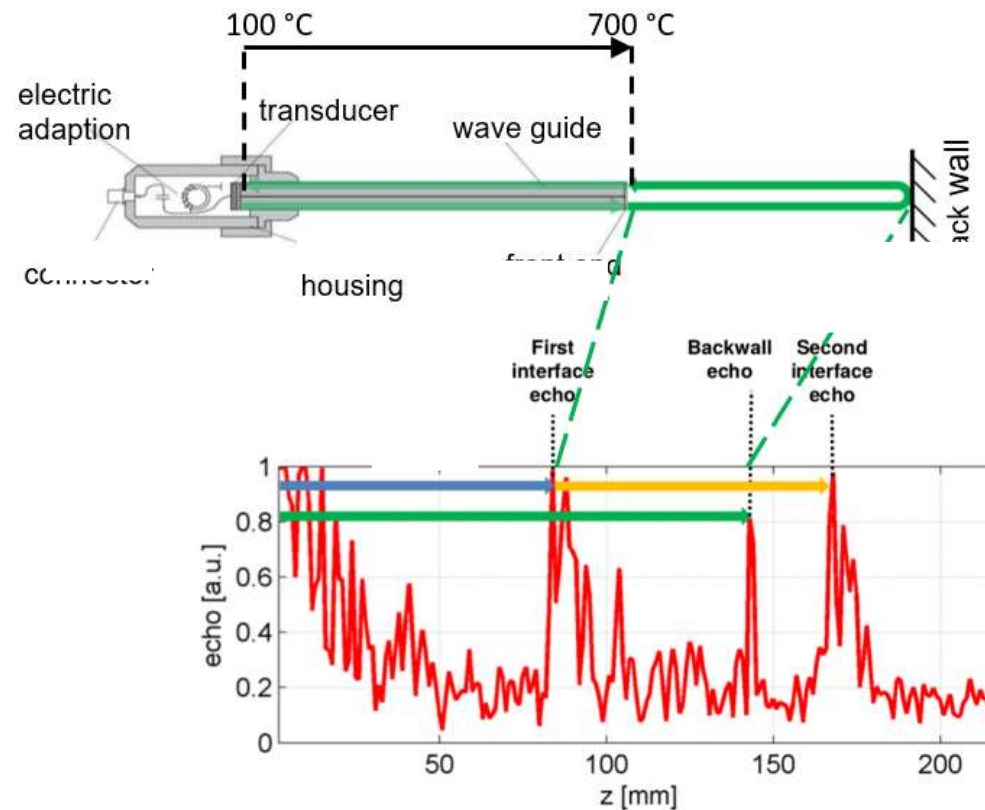
UDV: High temperature probes

- Temperature < 230°C
- Housing
 - protection from chemical corrosion
 - simple probe exchange during operation
 - removable for renewal of wetting
 - spring compensate thermal expansion
 - special treatment of housing tip to ensure wetting
- Measurement in a SnBi melt at 200 °C



UDV: Wave guide sensor

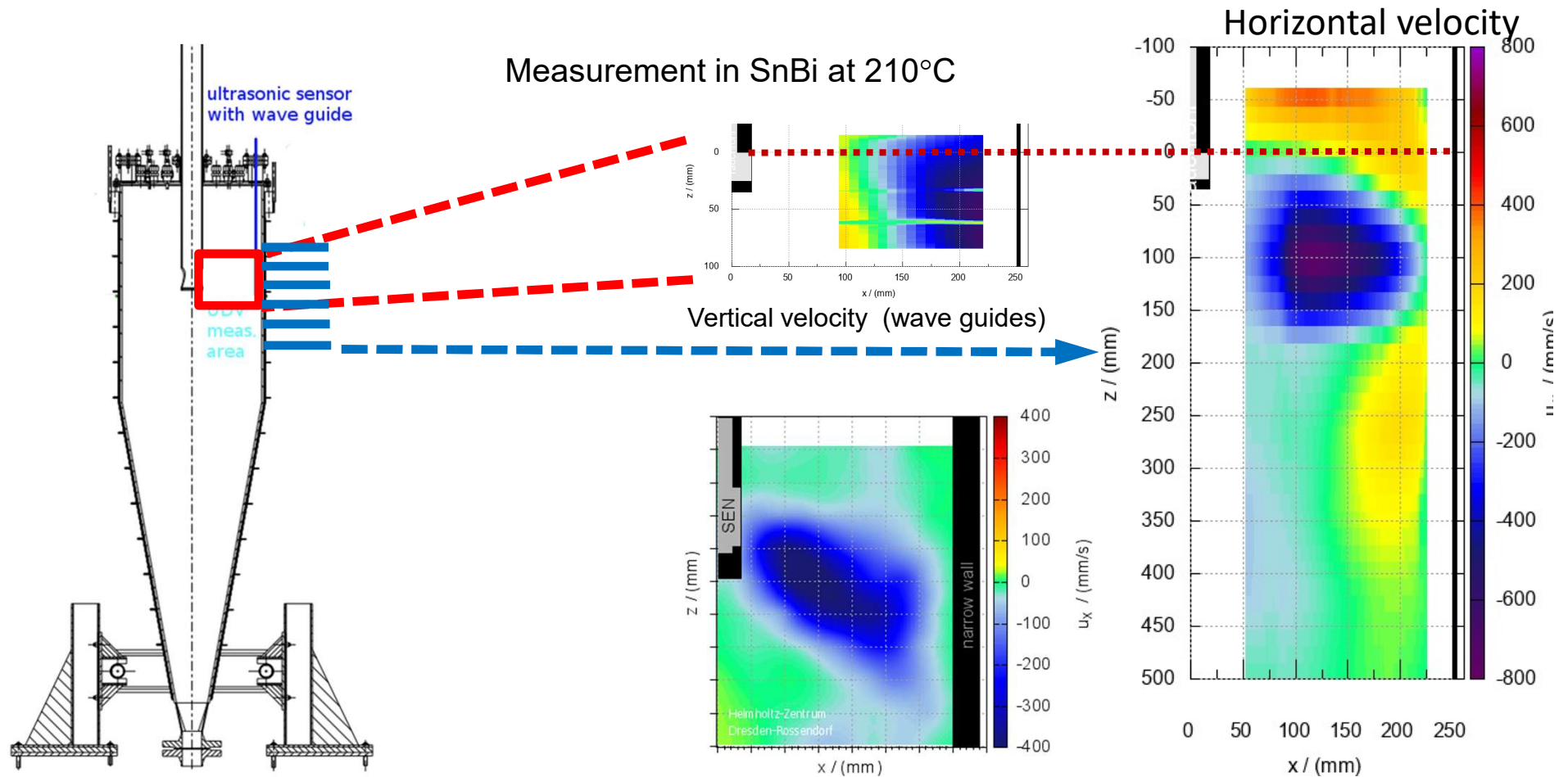
- Temperature $< 700\text{ °C}$
- Temperature gradient along wave guide
- Wave guide made of stainless steel foil (0.1 mm) axially wrapped
- Special treatment of the wave guide tip to ensure good wetting
- Prevent unwanted propagation modes



corrosion



UDV: Example at LIMMCAST



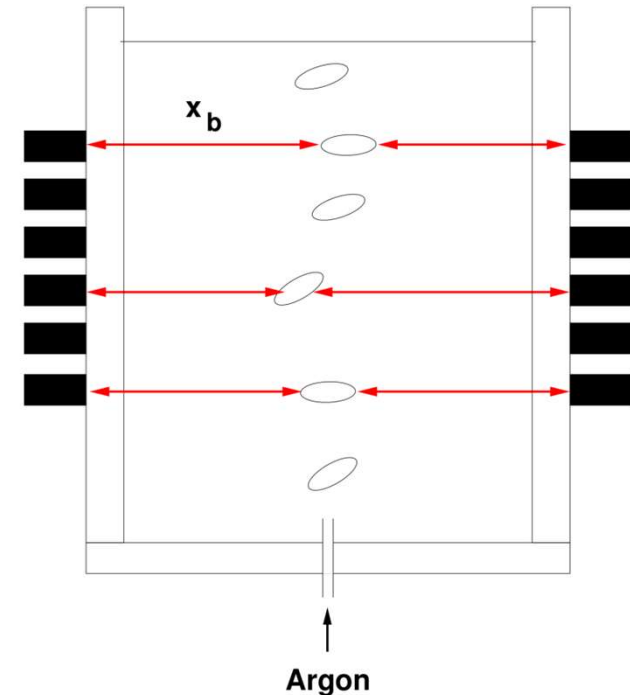
Ultrasound transit time technique (UTTT)

- Measurement procedure for one sensor:
 1. Send ultrasound impulse into the melt
 2. Listen to the echo
- Reflection at the outer surface of the bubble
- Measure time of flight of the impulse: t_b
- Distance between sensor and outer surface x_b :

$$x_b = \frac{ct_b}{2}$$

c sound velocity

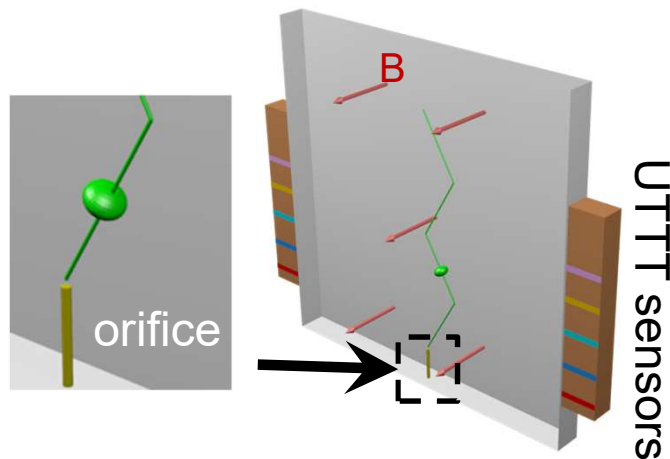
- Information:
 - Spatial distribution of bubbles
 - Velocity of bubbles
 - Bubble diameter



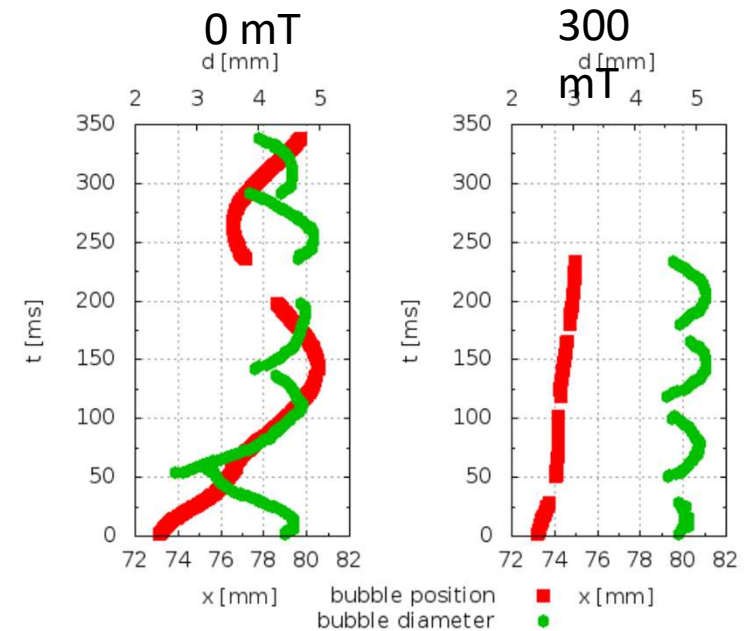
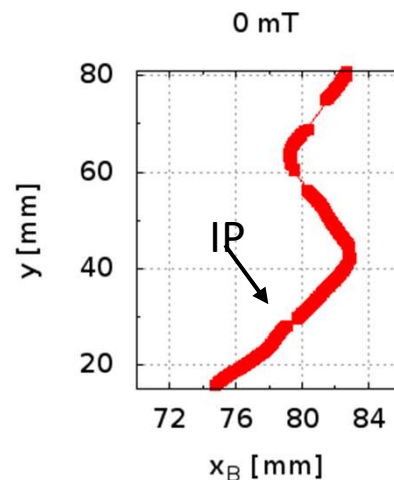
■ T. Richter et al., Nucl. Eng. Des. 291 (2015)

UTTT: Example in GaInSn path of single bubbles

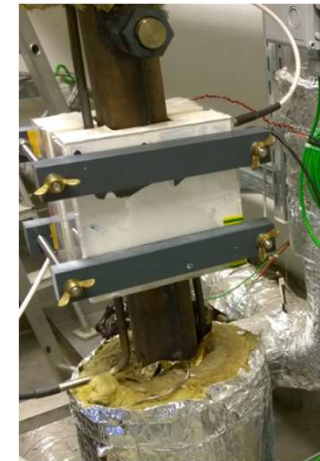
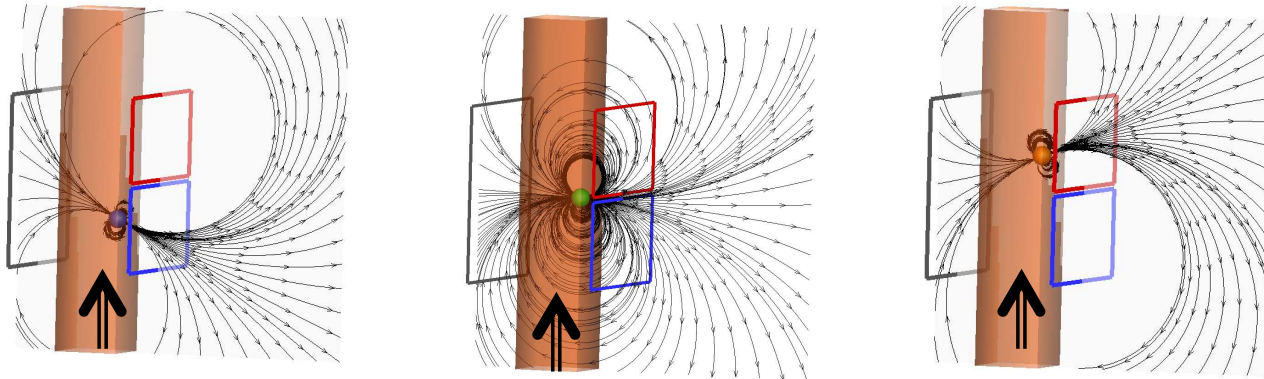
- Flat vessel: 144 mm × 12 mm with h = 144 mm
- Static magnetic field perpendicular to the wide face of the container 0 – 300 mT
- Comparison with X-ray radiography
- Measurement at 5 vertical positions
- Bubble diameter
 - 0 mT: d = 4.8 mm
 - 300 mT: d = 5.2 mm



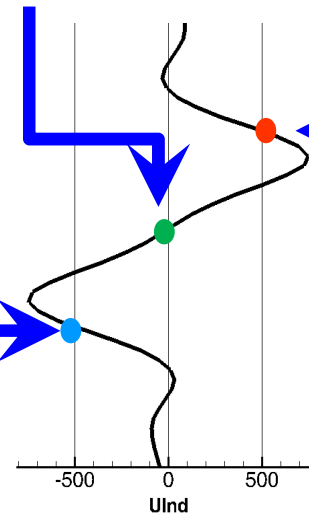
T. Richter et al., IJFM 104 (2018)




Inductive bubble detection



- Transmitting coil (black), frequency 10 – 200 Hz
- Planar gradiometer on opposite side (red and blue)
- Measured signal is zero, if the pipe is only filled with metal

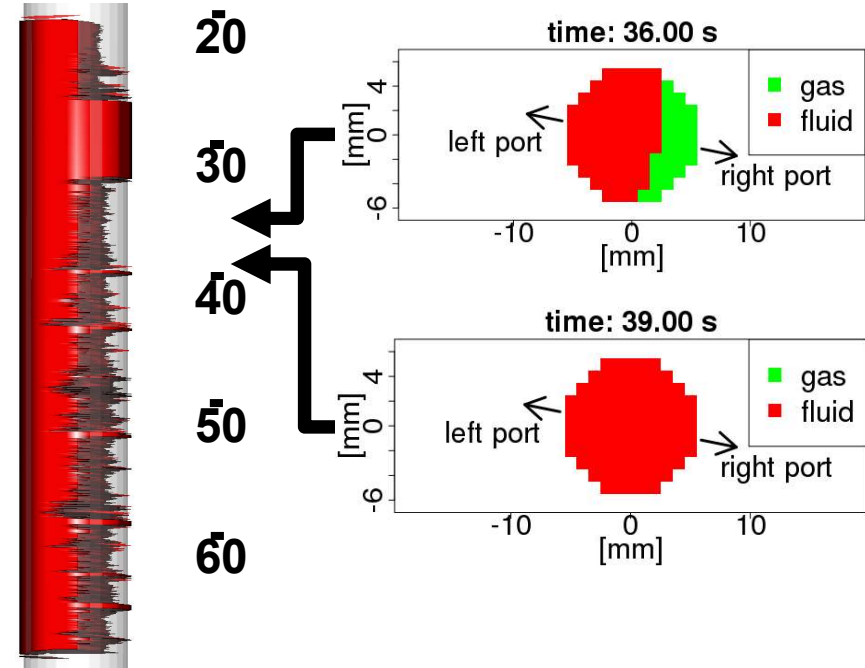
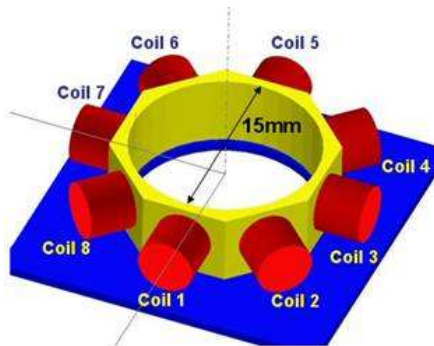


- Bubble deforms eddy currents inside the melt
- Deformed magnetic field is recorded by the sensor
- Typical S-shaped signal for a single bubble traversing the sensor volume

 T. Gundrum et al., Sensors 16 (2016)

Mutual inductance tomography (MIT)

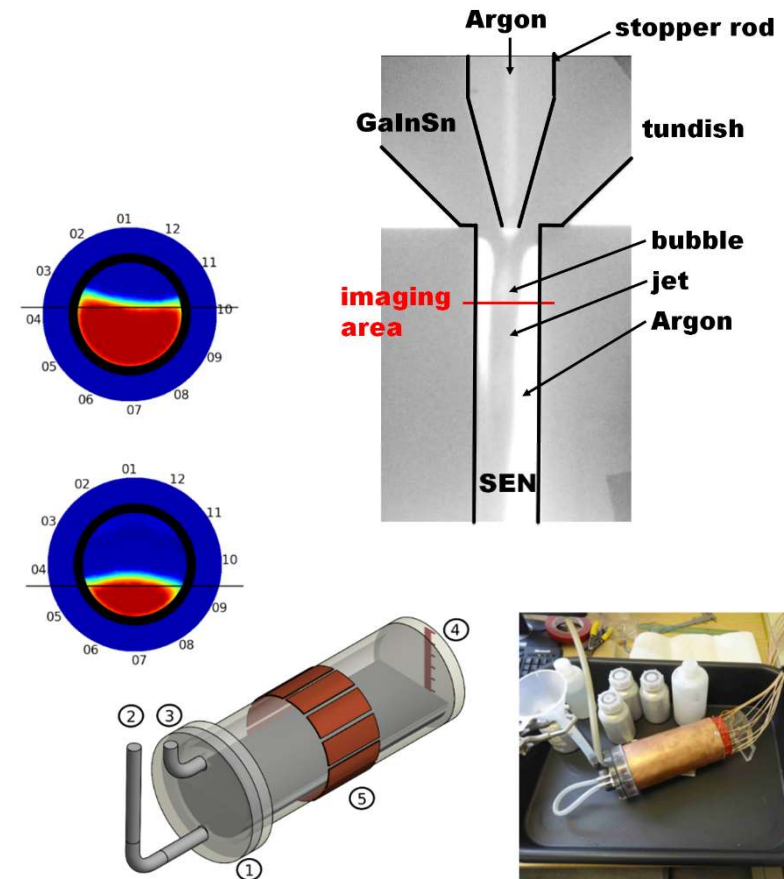
- Developed at the University of Manchester
- Measurement of the conductivity distribution in one cross section
- 8 sensing coils
- Temporal resolution about 20 – 40 frames per second
- Nonlinear inverse problem



- N. Terzija et al., Flow Meas. Instrum. 22 (2011)
- T. Wondrak et al., MMTB 42 (2011)

Two phase flows in pipes

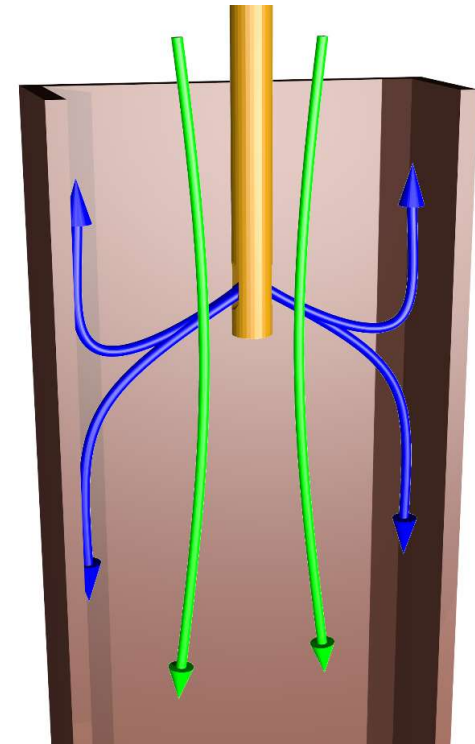
- Argon gas / liquid steel distribution:
 - Shape of the jet
 - Bubbles inside the jet
- Difficult to reconstruct **both** properties at the same time using only MIT
- In collaboration with University of Bath:
 - Capacitance tomography:** shape
 - MIT:** bubbles
- Feasibility study for the application of capacitance tomography for liquid metals



 T. Wondrak et al., Meas. Sci. Technol. 28 (2017)

Contactless Inductive Flow Tomography (CIFT)

1. Exposing the flow \mathbf{v} to an externally applied magnetic field \mathbf{B}



■ M. Ratajczak et al, Philos. Trans. R. Soc, A 374 (2016)

■ T. Wondrak et al., Flow Meas. Instrum. 62 (2018)



HZDR

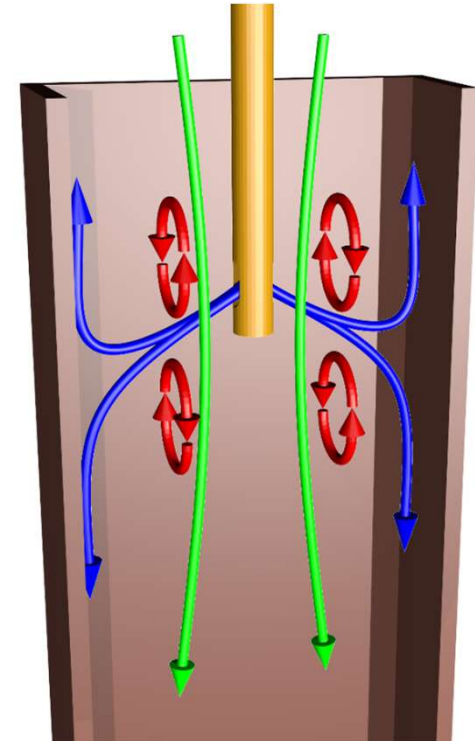
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Contactless Inductive Flow Tomography (CIFT)

1. Exposing the flow \mathbf{v} to an externally applied magnetic field \mathbf{B}
2. Induced current:

$$\mathbf{j} = \sigma(\mathbf{v} \times \mathbf{B} - \nabla\varphi)$$



 M. Ratajczak et al, Philos. Trans. R. Soc, A 374 (2016)

 T. Wondrak et al., Flow Meas. Instrum. 62 (2018)



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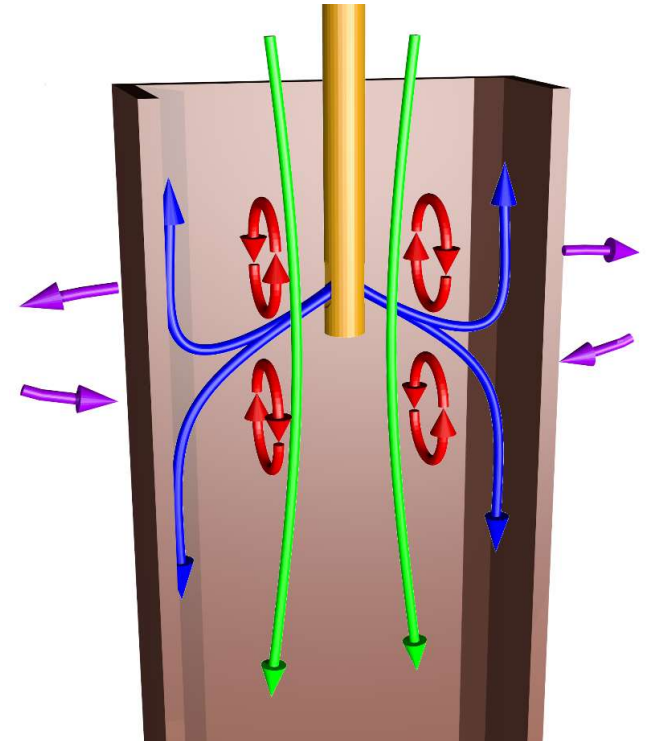
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$$\mathbf{j} = \sigma(\mathbf{v} \times \mathbf{B} - \nabla\varphi)$$

3. Flow Induced magnetic field

$$\mathbf{b}(\mathbf{r}) = \frac{\mu_0\sigma}{4\pi} \iiint_V \frac{(\mathbf{v}(\mathbf{r}') \times \mathbf{B}(\mathbf{r}') - \nabla\varphi(\mathbf{r}')) \times (\mathbf{r} - \mathbf{r}')}{|\mathbf{r} - \mathbf{r}'|^3} dV'$$



■ M. Ratajczak et al, Philos. Trans. R. Soc, A 374 (2016)

■ T. Wondrak et al., Flow Meas. Instrum. 62 (2018)



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Contactless Inductive Flow Tomography (CIFT)

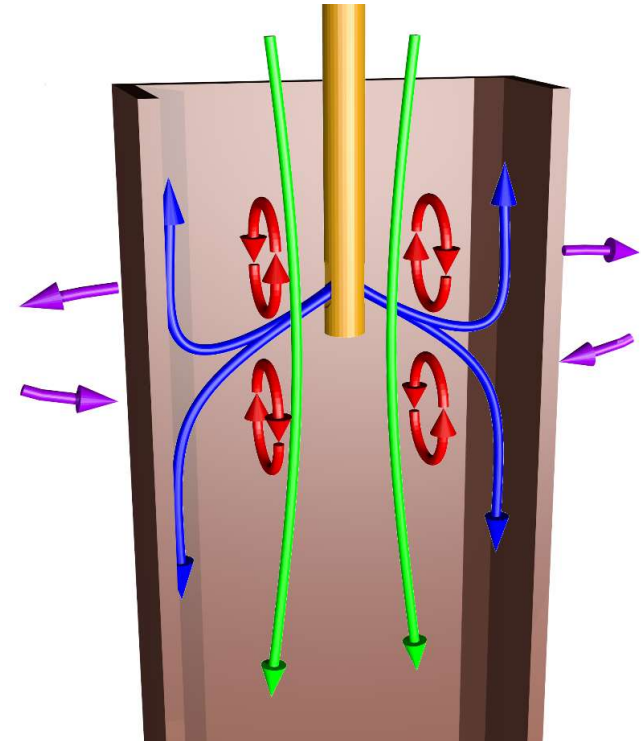
1. Exposing the flow \mathbf{v} to an externally applied magnetic field \mathbf{B}
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4. Measurement of the magnetic field outside the melt



■ M. Ratajczak et al, Philos. Trans. R. Soc, A 374 (2016)

■ T. Wondrak et al., Flow Meas. Instrum. 62 (2018)



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Contactless Inductive Flow Tomography (CIFT)

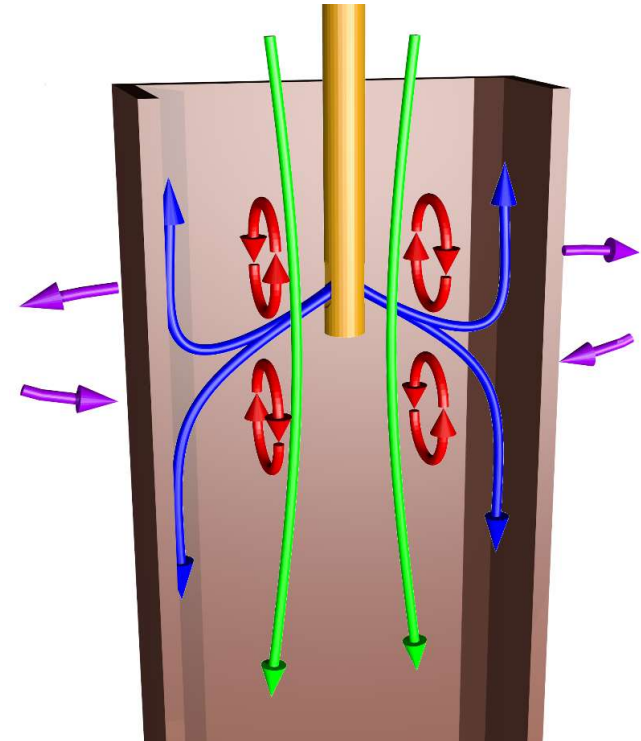
1. Exposing the flow \mathbf{v} to an externally applied magnetic field \mathbf{B}
2. Induced current:

$$\mathbf{j} = \sigma(\mathbf{v} \times \mathbf{B} - \nabla\varphi)$$

3. Flow Induced magnetic field

$$\mathbf{b}(\mathbf{r}) = \frac{\mu_0\sigma}{4\pi} \iiint_V \frac{(\mathbf{v}(\mathbf{r}') \times \mathbf{B}(\mathbf{r}') - \nabla\varphi(\mathbf{r}')) \times (\mathbf{r} - \mathbf{r}')}{|\mathbf{r} - \mathbf{r}'|^3} dV'$$

4. Measurement of the magnetic field outside the melt
5. Reconstruction of the velocity field from the measured induced magnetic fields (linear inverse problem)



■ M. Ratajczak et al, Philos. Trans. R. Soc, A 374 (2016)

■ T. Wondrak et al., Flow Meas. Instrum. 62 (2018)

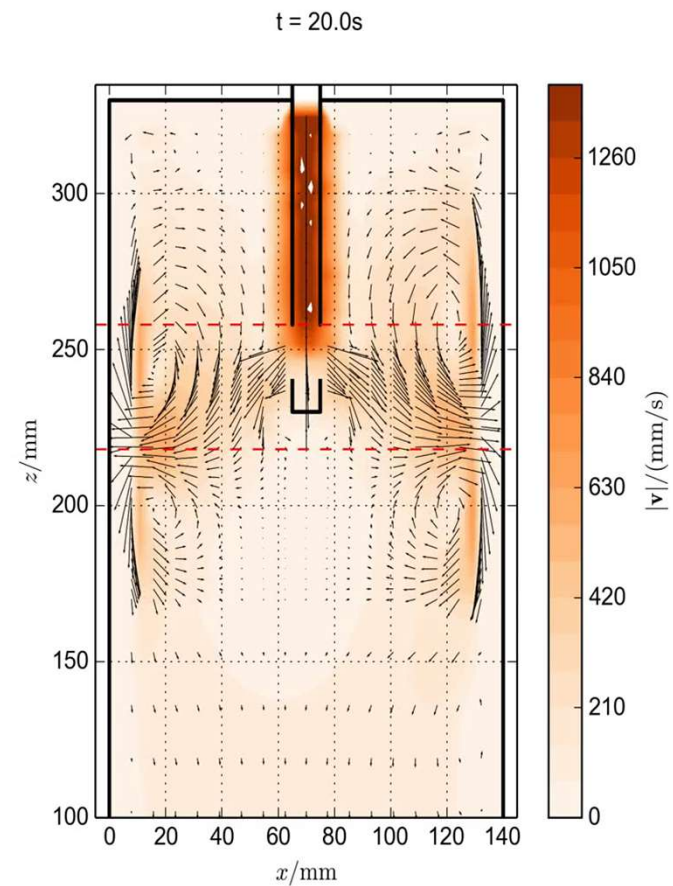
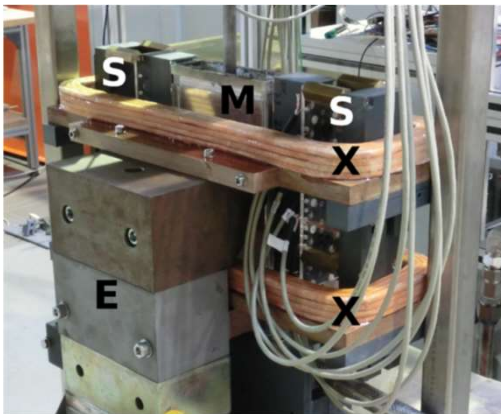
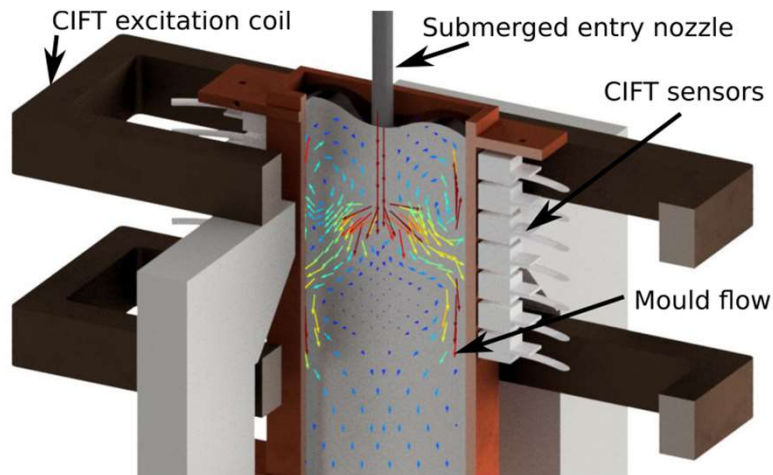


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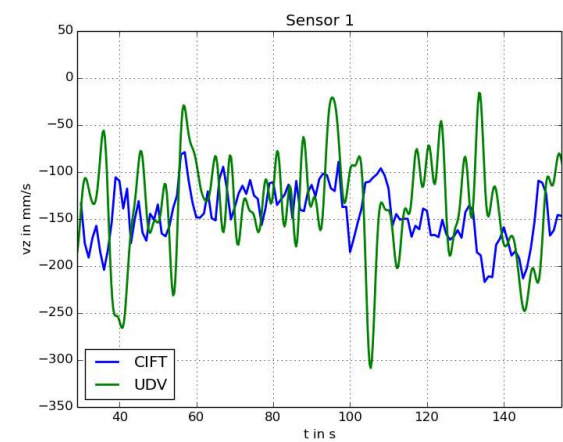
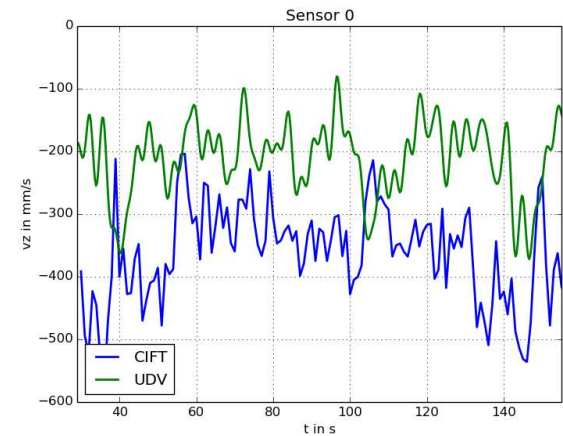
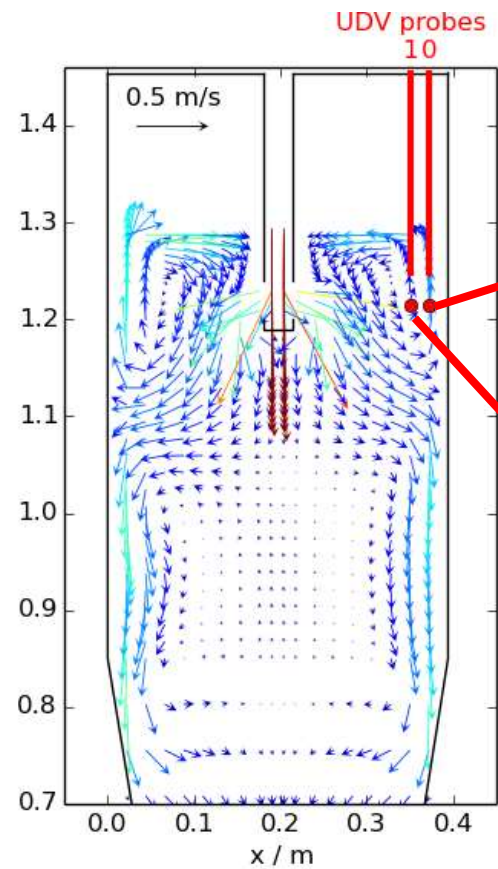
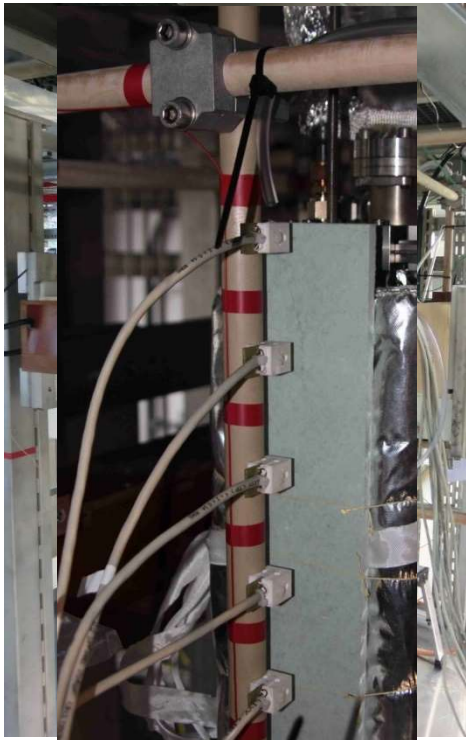
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CIFT with electromagnetic brake

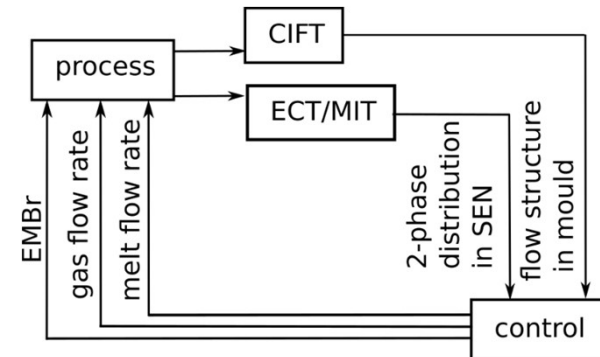
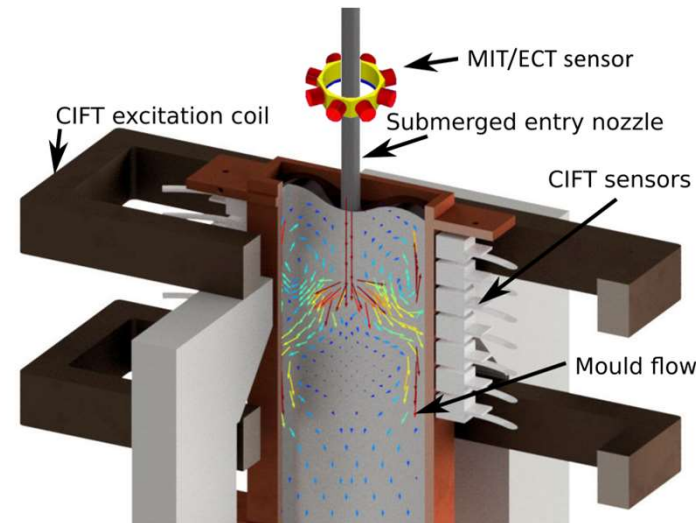


Example LIMMCAST

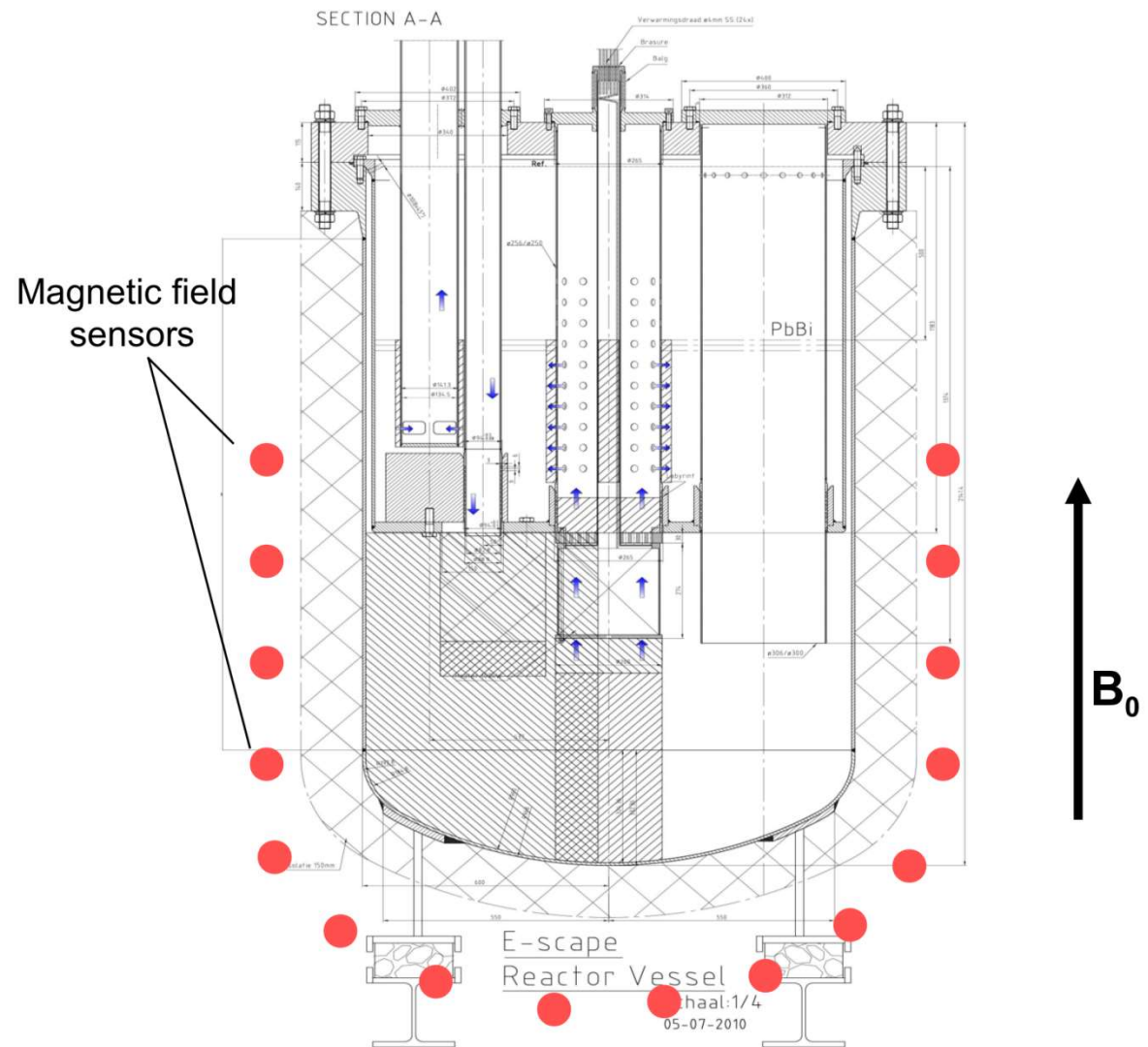
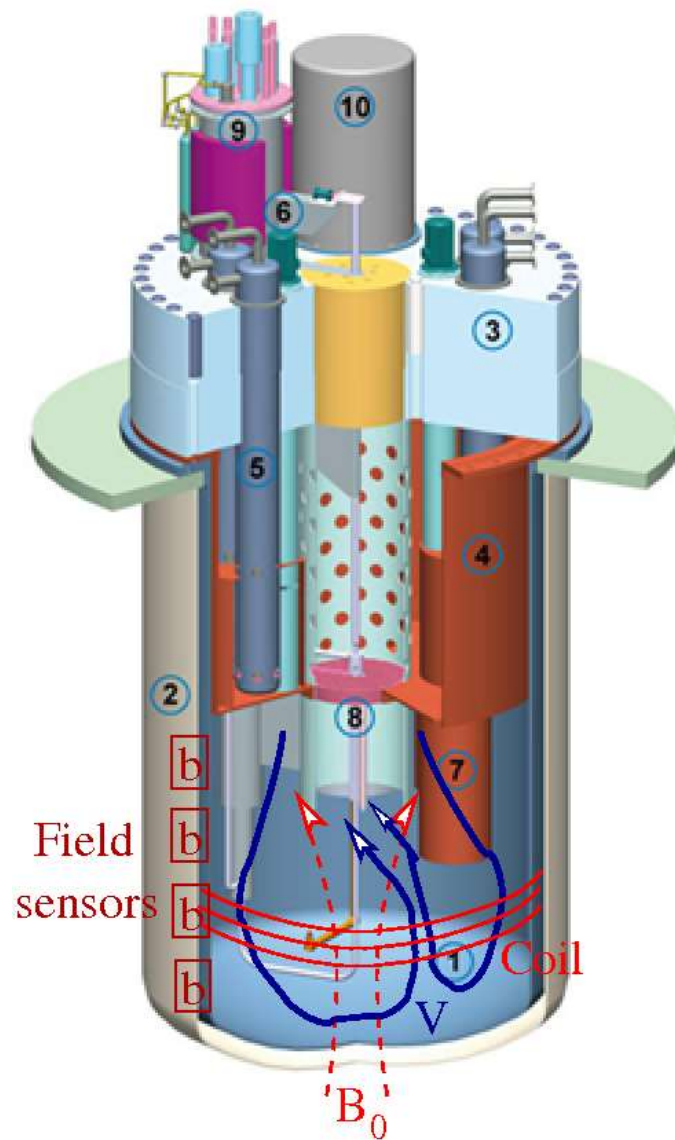


Tomographic sensors for control

- European Training Network:
Smart tomographic sensors for
advanced industrial process
control (TOMOCON)
- **Tomographic measurement**
 - CIFT: flow in the mould
 - MIT/ECT: two-phase flow in
SEN
- **Actuators**
 - Gas injection
 - Strength of the EMBR
- **Control objectives**
 - Double roll preferred
 - No asymmetric flow
 - Constant position of the jet
 - Constant filling degree of the
SEN
 - Constant velocity at the
meniscus

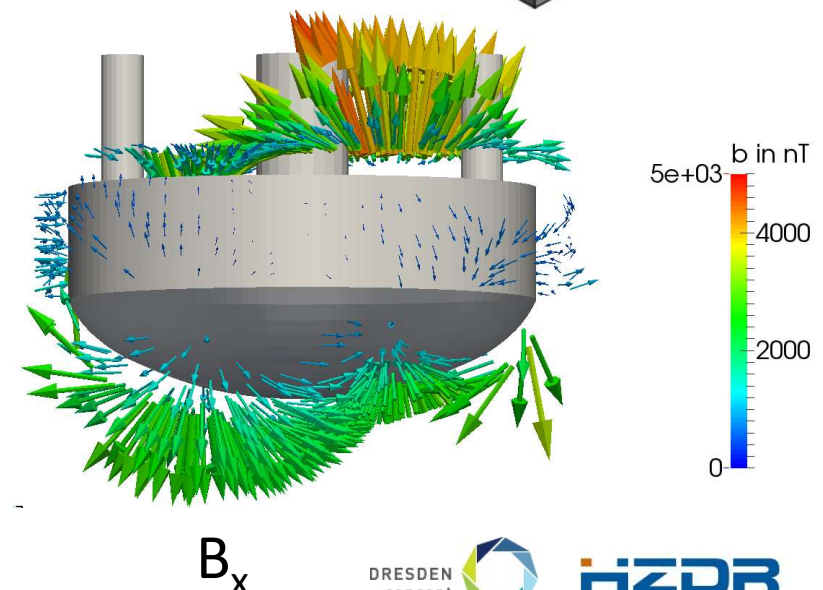
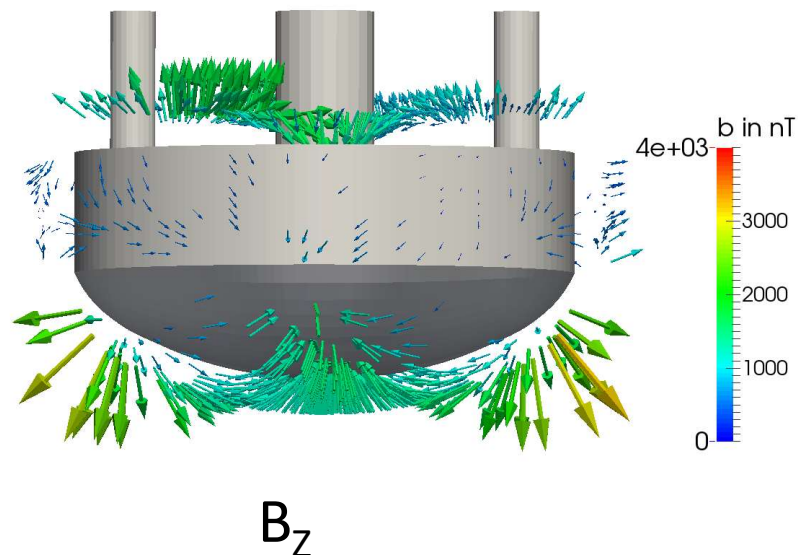
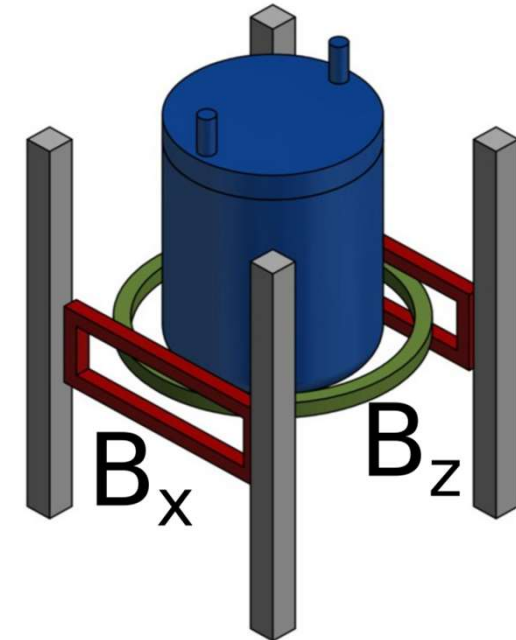


Proposal of the application of CIFT to ESCAPE



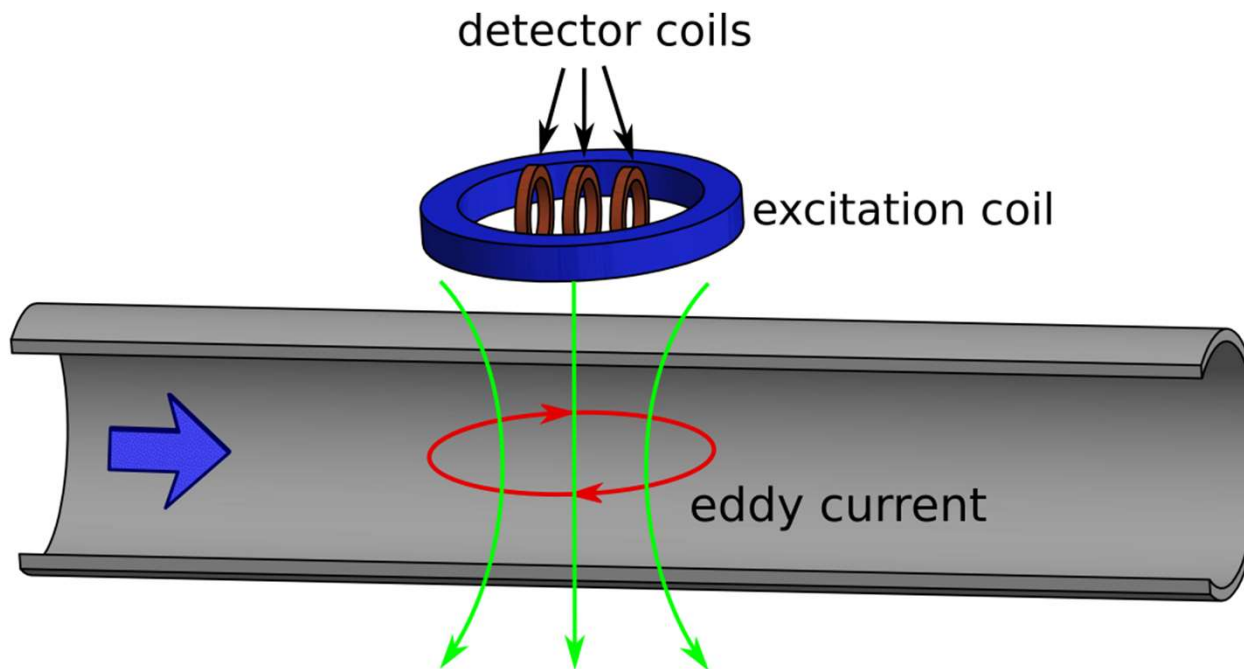
CIFT for ESCAPE: Forward problem

- Two applied magnetic fields (1 mT)
- Frequency 0.5 Hz
- Flow induced magnetic field: 1 μT



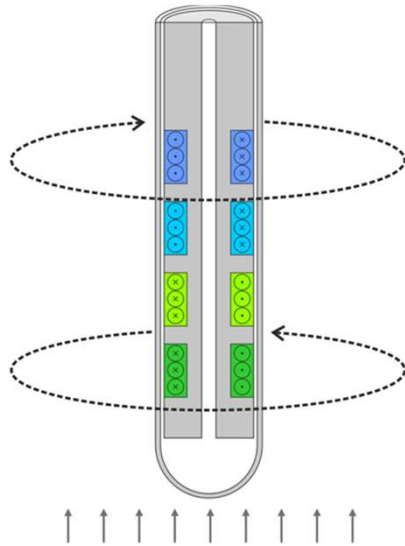
Transient eddy current flow meter (TEC-FM)

- Pulsed external magnetic field generates a transient eddy current
- Continuous tracking of a flow-advected transient eddy

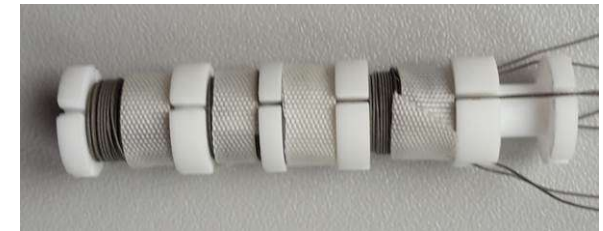
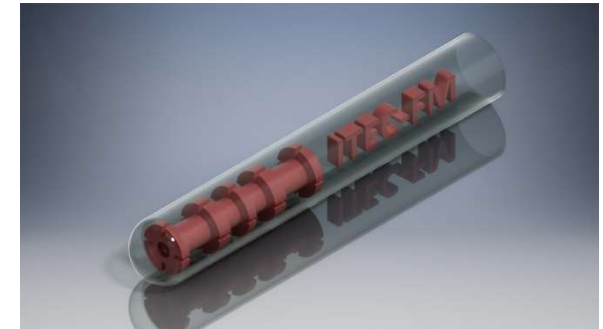
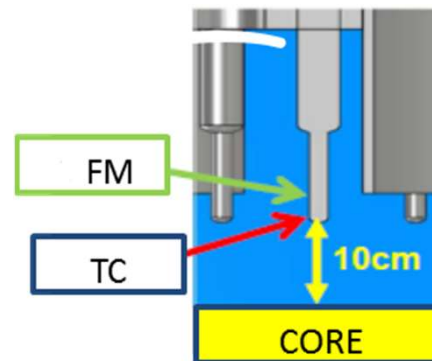
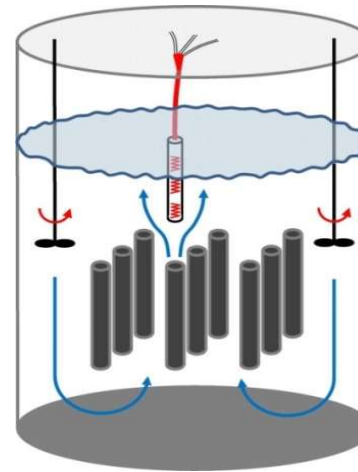


■ J. Forbriger et al., Meas. Sci. Technol. 26 (2015)

Immersed sensor (ITEC-FM)

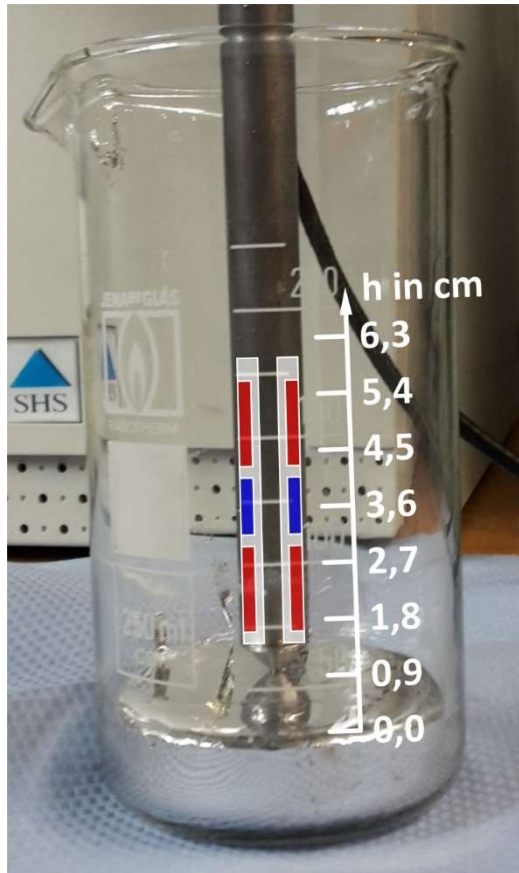


- Immersed TEC-FM for the purpose of local blockage detection
- 2 excitation coils
- 2 detection coils

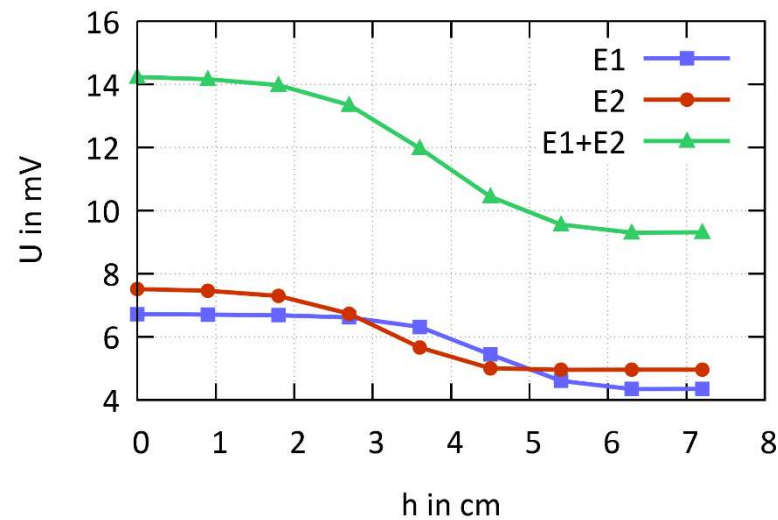


■ N. Krauter et al., Meas. Sci. Technol. 28 (2017)

Immersed level sensor

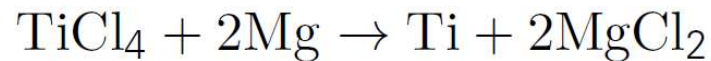


- preliminary measurement with velocity sensor in GaInSn
- linear dependency of $U(h)$ between 2,7 cm and 4,5 cm

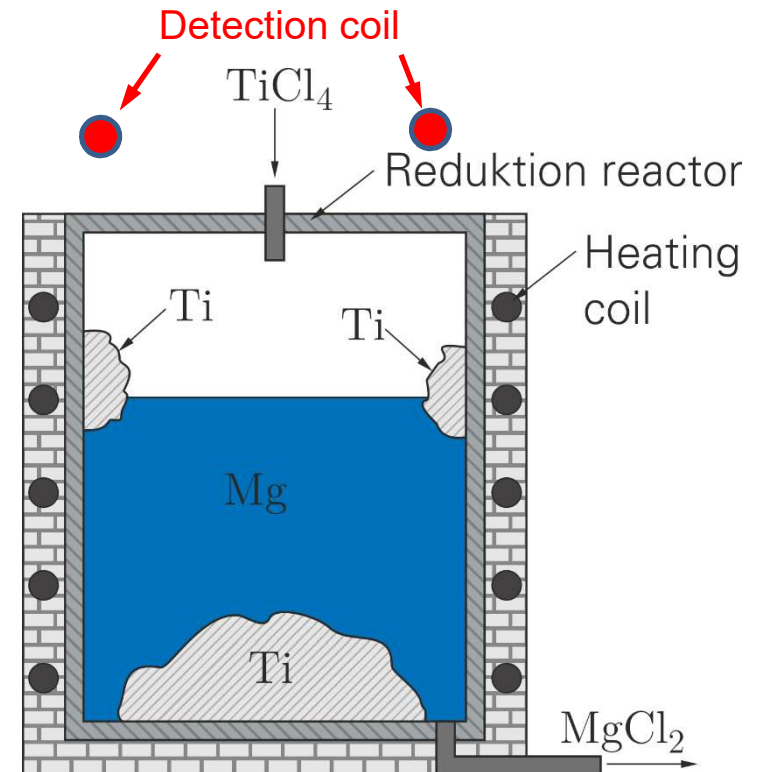


Level measurement for titanium production (Kroll process)

- Exothermal reaction on the free surface of liquid Mg



- Temperature of 850 °C
- Titanium sponge deposits on the bottom and walls of the reduction reactor
- Titanium sponge interferes with the inductive level measurement because it has a similar electrical conductivity to liquid magnesium
- Heating coils are excitation coils
- One large coil** at the top of the reactor
- Non linear inverse problem:
database containing the induced voltage for a huge range of parameter combinations

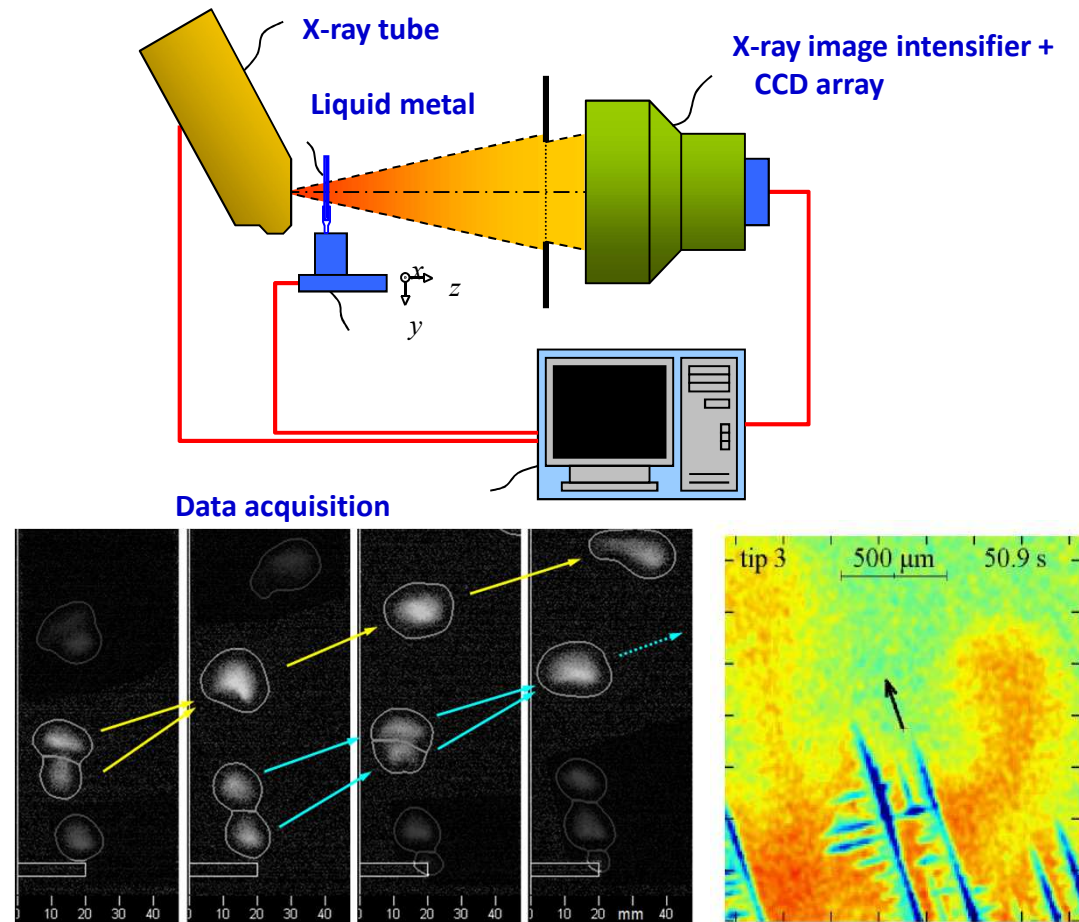


N. Krauter et al., MMTB 49 (2018)

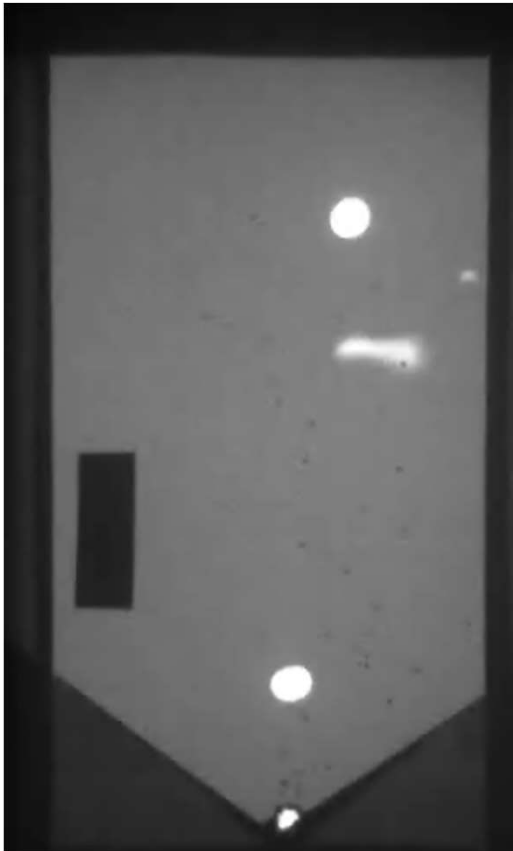
X-ray radiography

- Attenuation of the X-ray depends on the density ρ of the material
- Visualization of bubbles
 - bubble size and shape
 - bubble trajectory
- Visualization of solidification
- High density of liquid metals:
GaInSn: < 15 mm thickness

■ *N. Shevchenko et al.,
J. Cryst. Growth 417 (2015)*

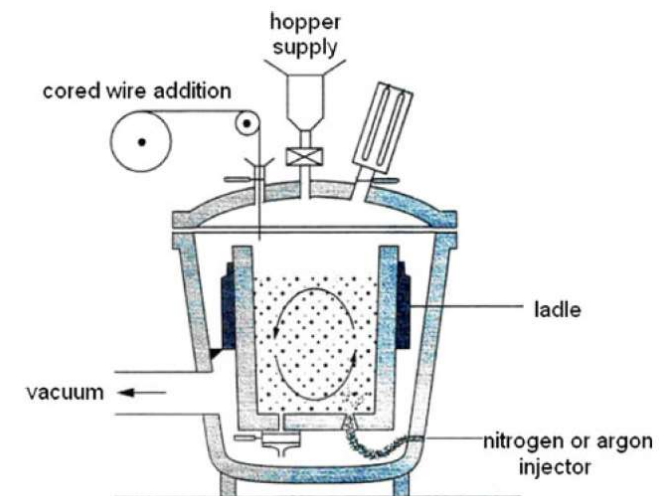


Liquid metal flotation



- Removal of inclusions
- Shear-driven coalescence of particles
- Particle capturing by rising gas bubbles

Cooperation with Technical University Dresden
+ French partners (Nancy and St. Etienne)



Background: Flow control during solidification

Melt flow: natural convection (thermal, solutal)
Forced convection (electromagnetic stirring)



**Freckle formation triggered by
mesoscopic convection**

**Freckle defect in
a turbine blade**



[A.F. Giamei (1997)]

Conclusions

- Flow measuring in liquid metal flows is still a challenging task
- Some progress has been achieved in recent years
- Velocity fields can be measured now with reasonable temporal and spatial distribution, however, technical solutions for a robust instrumentation under industrial conditions are still rare



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Many thanks for your attention!



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